

Fig. 1

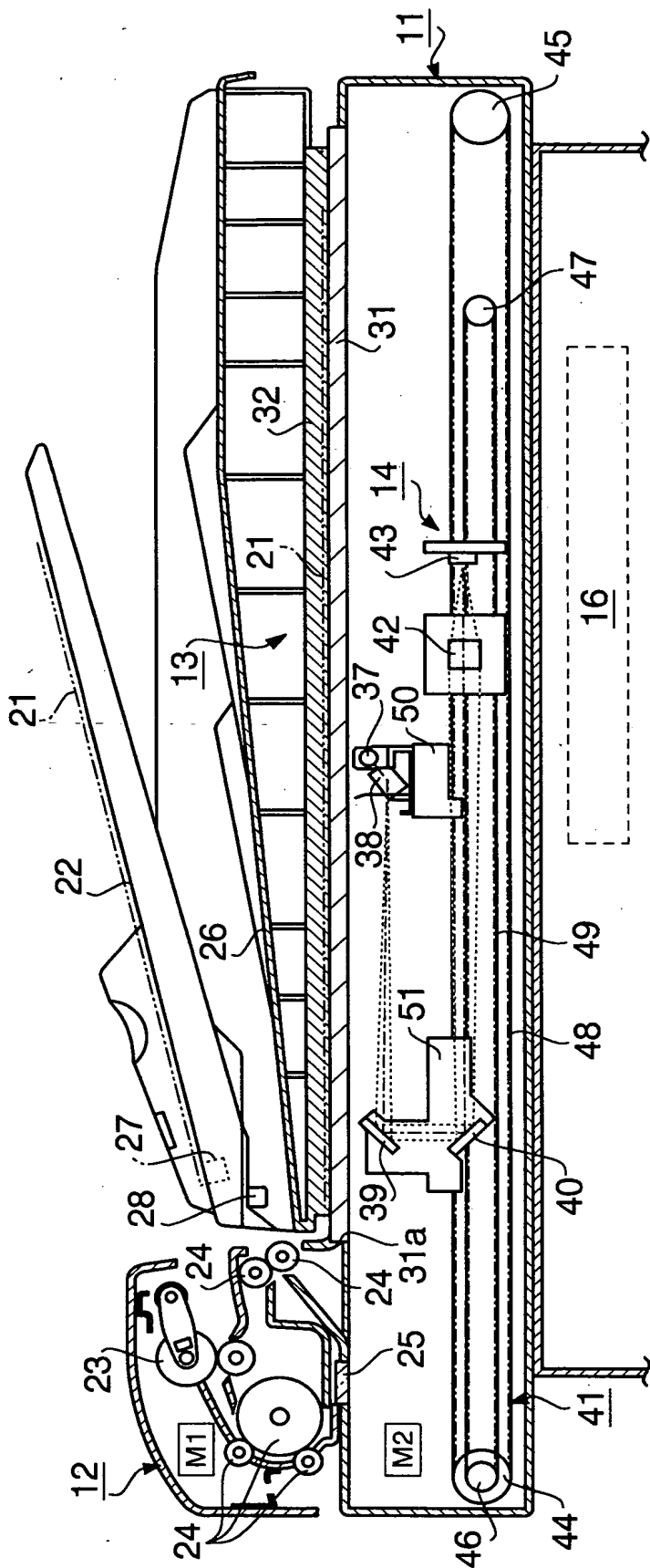


FIG. 2

FIG. 3

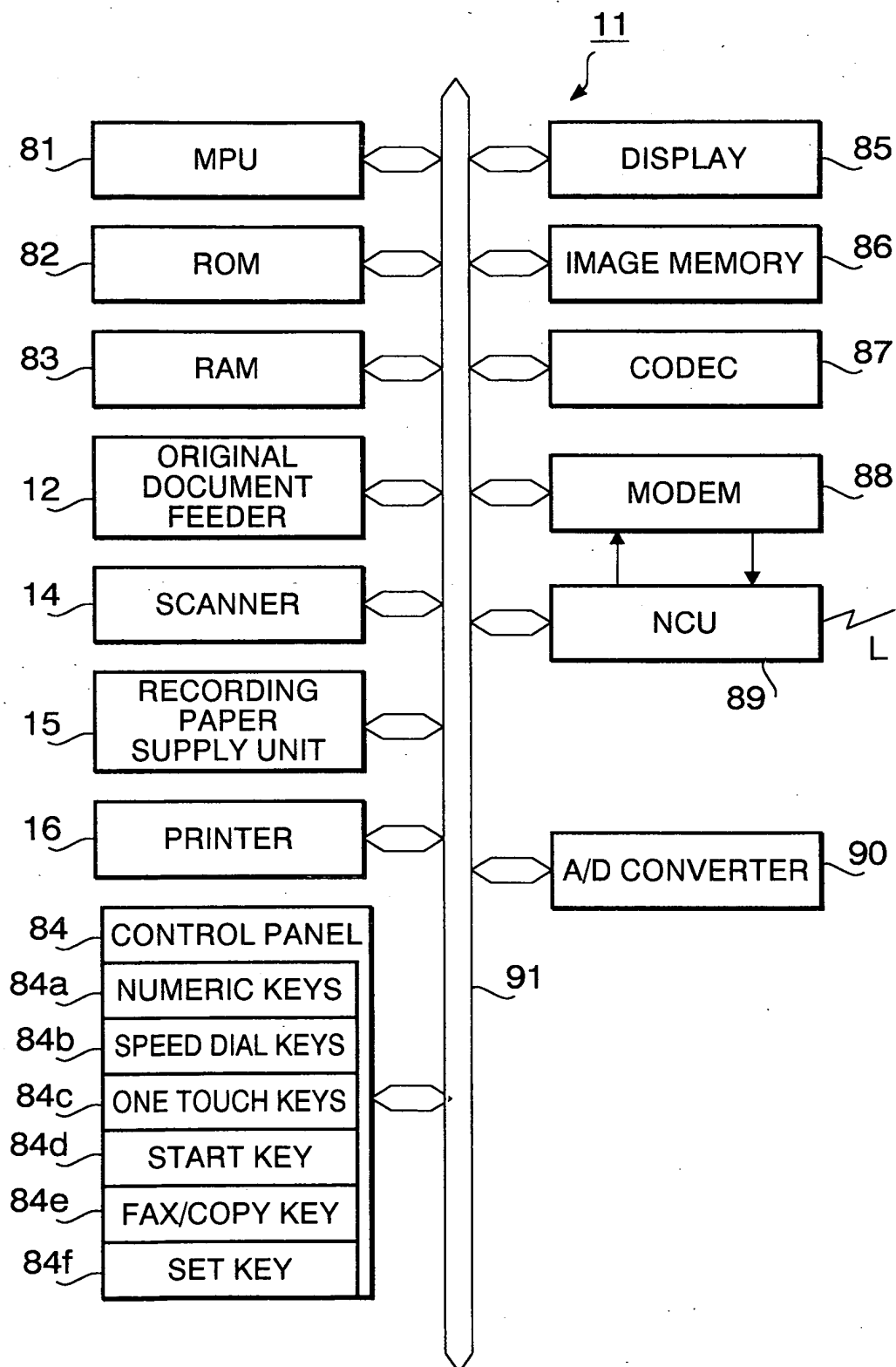


FIG. 4 is a block diagram of a motor control system 100(200) according to an embodiment of the present invention. The system 100(200) includes a CPU 81, a motor driver 101(201), and a motor 102(202). The CPU 81 is connected to the motor driver 101(201) and the motor 102(202). The motor driver 101(201) is connected to the motor 102(202) and a power source +B. The motor 102(202) is connected to the power source +B. The system 100(200) also includes a motor 103(203), a motor 104(204), and a motor 105(205). The CPU 81 is connected to the motor driver 101(201) and the motors 103(203), 104(204), and 105(205). The motor driver 101(201) is connected to the motors 103(203), 104(204), and 105(205). The motors 103(203), 104(204), and 105(205) are connected to the power source +B.

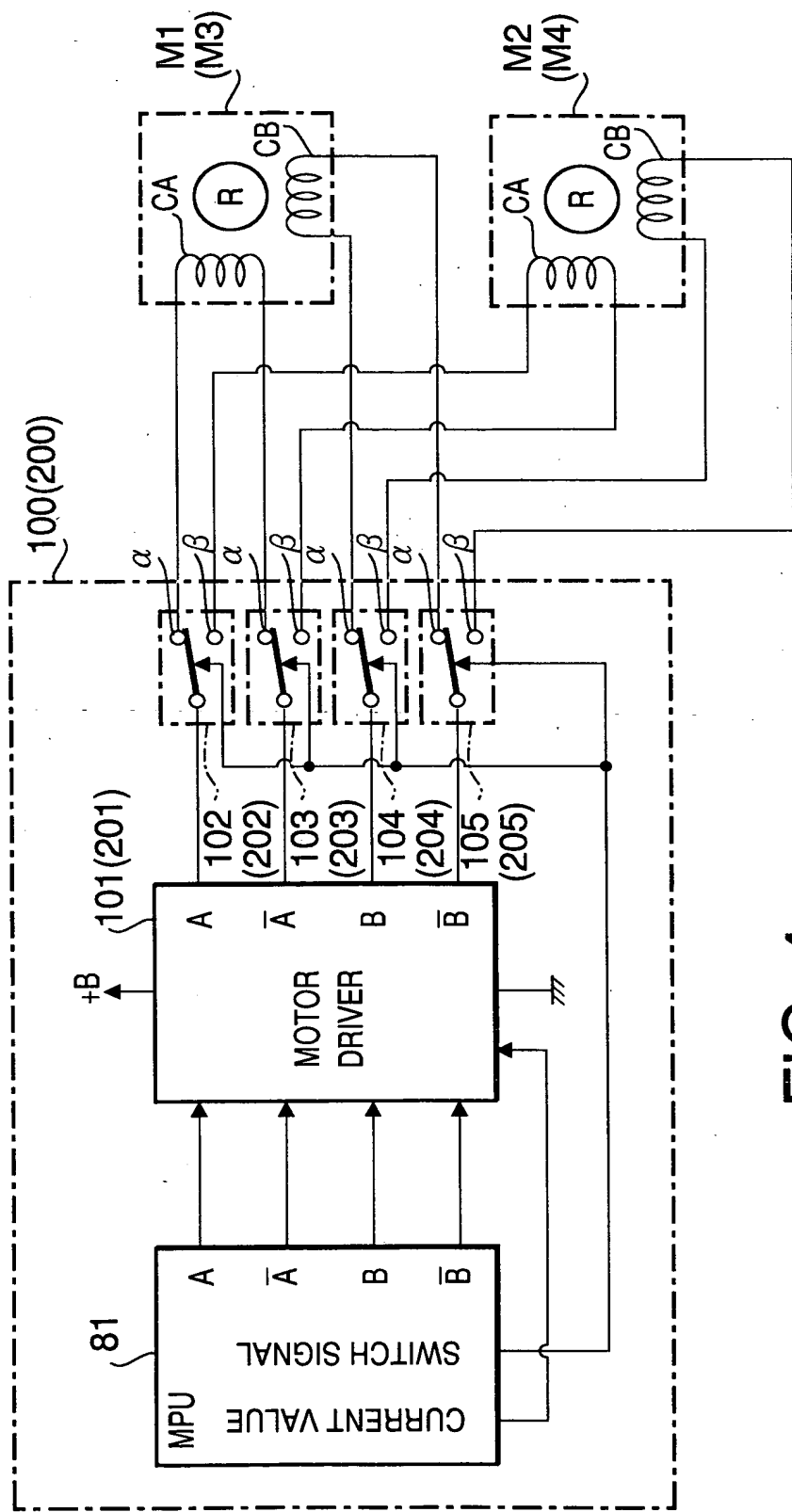


FIG. 4